## Characteristics of the Dynamic of Mobile Networks

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### ENS Lyon/LIP - INRIA/D-NET

Workshop: Dynamical Complex Systems December 2009, Buenos Aires, Argentina http://cnet.fi.uba.ar/wdcs/







### Outline

### MOSAR Project

Project overview

### Dynamic Network Characterization

- Motivation
- Statistical analysis of snapshots of graphs
- Towards a global analysis of the dynamics
- Modeling of the dynamics

### • Conclusion

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# Deployment of a large-scale dynamic networks

Control of antimicrobial resistance of bacteria responsible for major and emerging nosocomial infections.

#### **MOSAR Experiment**

- Medical / staff / Patients (500 people)
- Individual antibiotic use;
- Characterization of the isolates bacteria and their epidemicity;
- 7/24 during 6 month long period

#### Document contact frequencies

- Associate 1 sensor with each actor
- monitor the dynamic (inter & intra contact)















Overview



Overview



### Multi modal / multi time scale



**0**38

03

06 •16

**0**40





#### E. Fleury

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### **Objectives**

#### MOSAR project

- Better understand the intrinsic characteristics / properties of dynamic networks
- Model / analyze interaction between node/users
- Describe accurately the dynamics



#### Two central questions:

- Obtaining random models that reproduce "these" properties
- How do their functionalities constrain the structures of real network?

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### Preliminary data<sup>1</sup>

Mosar experiment: May 2009 - Nov 2009.

#### "Toy" traces are now available

- 41 nodes, 3 days (254 151 sec), every 120sec
- 820 possible links,

"[...] inter contact time distribution can be compared to the one of power law [...]"



<sup>A</sup>. Chaintreau and J. Crowcroft and C. Diot and R. Gass and P. Hui and J. Scott, *Impact of Human Mobility on the Design of Opportunistic Forwarding Algorithms*, INFOCOM 2006

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### Methodology

### Descriptive: Standard graph properties

- 1 as a function of time to to provide an empirical statistical characterization of the dynamics.
- 2 temporal evolution of the snapshots
- statistical signal processing

#### Analysis: global indicators

connected components, triangles, and communities

#### Model

 We propose models to perform random dynamic networks simulations.

### **Standard graph properties**

### Snapshots $G_t = (V^0, E_t)$

- Active links:  $E(t) = |E_t|$
- ► Connected vertcices:  $V(t) = |\{u \in V^0, d_{G_t}(u) > 0\}|$
- Average degree of connected vertices is  $D(t) = \sum_{u \in V^0} d_{G_t}(u) / V(t)$
- Number of connected components (maximal subgraph such as every node of the subgraph is connected to each another node): N<sub>c</sub>(t) = |C<sub>Gt</sub>|

• Number of triangles: 
$$T(t) = |T_{G_t}|$$

	IMOTE			
Property		Mean	Std. Dev.	Corr.
				Time (s)
#Active links	E(t)	21.9	12.4	5200
#Connected vertices	V(t)	19.9	4.7	7400
Avg degree	D(t)	2.1	0.8	3600
#CC	$N_c(t)$	4.8	2.1	5600
#Triangles	T(t)	6.9	8.30	4700

#### Probability distribution

- time bin of 1s << period.</p>
- PDF obtained are not heavy tailed
- variability is not very large (stdv is a good measurement of the variability)



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#### Network is sparse

- less than 10% of active links among the 820 possible links
- at no time the network is a single connected component.
- many nodes remain isolated during long times (around 50% on average for daytime and more than 90% for nighttime).



### differential sequence: DS[k] = D[k + 1] - D[k]

- log-log representation of the covariance in the wavelet domain<sup>a</sup>
- S<sub>i</sub> is roughly the average of the wavelet coef. at scale j
- Hurts exponent is close to the special value 0.5.
- ▶ no long range → Independent Identically Distributed (IID)







#### Large number of triangles

- $\mathbb{E}(T(G(p, n))) = \binom{N}{3} 3! p^3 \& \mathbb{E}(E(G(p, n))) = p \frac{N(N-1)}{2}$
- ▶ When there is k links,  $\mathbb{E}(T(G(n,k))) \sim \frac{8k^3(N-2)}{N^2(N-1)^2}$
- ▶ 70 links (max) → 40(60)

▶ 22 links (avg) 
$$\longrightarrow 1(7)$$

### **Dynamical characteristics**

### Correlation times

- temporal evolution (X(t): univariate time-series)
- ► The autocorrelation function of *X*(*t*):

$$C_X(\tau) = \langle X(t+\tau)X(t) \rangle_t - (\langle X(t) \rangle_t)^2$$

► correlation time: first time where the function C<sub>X</sub>(τ) goes to zero

#### notes

- correlation times of *E*, *V* and  $N_c$  are rather large: ~ 1h15.
- D and T have comparable correlation times.
- This suggests that these properties evolve under a common cause.

### **Dynamical characteristics (cont)**



Mean : 140;  $\alpha = 1.66$ 

Mean : 3680;  $\alpha = 0.60$ 

#### Contact and inter-contact durations

$$\blacktriangleright P[X > x] \underset{x \to \infty}{\sim} cx^{-\alpha}$$

- $\alpha > 2$ : finite mean/variance;  $\alpha < 2$ , infinite variance (*heavy tailed*).
- $\alpha < 1$ , infinite mean/variance.

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### Dynamics of links creation and deletion



►  $E_{\oplus}(t) = |\{e \in E_t, e \notin E_{t-1}\}|$ , the number of links added at time *t* 

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### Dynamics of links creation and deletion (cont)



►  $E_{\ominus}(t) = |\{e \in E_{t-1}, e \notin E_t\}|$ , the number of links removed at time *t* 

	ΙΜΟΤΕ			
Property Me		Mean	Std. Dev.	Corr. Time (s)
Edge creation	$E_{\oplus}(t)$	0.15	0.55	$680 \sim 12 min$
Edge delation	$E_{\ominus}(t)$	0.15	0.55	$680\sim 12 min$

#### **Cross-correlations**

- Strong influence E(t) over V(t);
- $N_c(t)$  related to E(t)
- Less related:  $N_c(t)$  and V(t)
- $E_{\oplus}(t)$  and  $E_{\ominus}(t)$ : mostly uncorrelated

	E(t)	V(t)	$N_c(t)$	D(t)	T(t)	$E_{\oplus}(t)$	$E_{\ominus}(t)$
E(t)	1	0.85	-0.56	0.95	0.90	0.19	0.15
V(t)	0.85	1	-0.20	0.70	0.66	0.15	0.11
$N_c(t)$	-0.56	-0.20	1	-0.70	-0.41	-0.16	-0.15
D(t)	0.95	0.69	-0.69	1	0.86	0.19	0.15
T(t)	0.90	0.66	-0.41	0.86	1	0.15	0.11
$E_{\oplus}(t)$	0.19	0.15	-0.16	0.20	0.15	1	0.03
$E_{\ominus}(t)$	0.15	0.11	-0.15	0.16	0.10	0.03	1

#### Joint distributions



variation of the # links is not constant over the # vertices



#### Link correlations

Most pairs of links have a very low correlation coefficient.



#### Markovian evolution

- Correlation time link creation/deletion is small
- Independent from the evolution of other graph properties
- 3 Links are independents

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#### Markovian evolution

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### Towards a global analysis of the dynamics

#### global properties

- not directly interpretable in the sequence of static graphs
- stability of connected components
- communities embedded in the network
- proportion of creation of triangles

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### **Triangles in the graphs**

	P <sub>+/tri+</sub>	$P_{+/tri=}$	$f_{+/tri+}$	$f_{+/tri=}$
Ιμοτε	44 %	56 %	6 %	94 %
RANDOM	10 %	90 %	5 %	95 %

#### links / triangles

- $P_{+/tri+}$ : link creation  $\rightarrow$  triangle
- $f_{+/tri+}$ : innactive link  $\rightarrow$  triangle
- 40% of link creations increase the number of triangles
- proportion of inactive links that would create a triangle is very low
- More potential links doesn not imply higher P<sub>+/tri+</sub>

### Modeling of the dynamics

#### Simulation algorithm

- transition model with Markovian property
- links e are independent
- state of the network
- links *e* changes with  $P_{tr}(e, G_t)$
- duration \(\tau(e)\) since the link \(e \) has last changed its status

#### Ingredients

- contact / inter contact duration distribution
- elaborated graph properties  $(E(t), V(t), N_C(t), D(t))$
- dynamical information (triangles)

### Modeling of the dynamics

```
Input: Simulation time
Output: Random Dynamic Graph
foreach Simulation Time Step t do
   foreach link e do
       P_{tr}(e, G_t) = TransitionProbability(e) given the state G_t;
       p_r = \text{Uniform}(0,1);
       if (p_r \leq P_{tr}(e)) then
          ChangeState(e);
       end
   end
end
```

### **Ingredients** I

### Contact distribution

- heavy-tailed distributions for contact P<sub>ON</sub> and inter-contact P<sub>OFF</sub> durations
- P<sub>+</sub>(τ): probability that one link that was OFF since τ (τ ≥ 1) is activated

• 
$$P_{ON}(\tau) = P_{-}(\tau) \times \prod_{i=1}^{\tau-1} (1 - P_{-}(i))$$

$$P_{-}(\tau) = \frac{P_{ON}(\tau)}{\prod_{i=1}^{\tau-1} (1 - P_{-}(i))}, \quad \tau \ge 2, \quad P_{-}(1) = P_{ON}(1)$$
(1)

$$P_{+}(\tau) = \frac{P_{OFF}(t)}{\prod_{i=1}^{\tau-1} (1 - P_{+}(i))}, \quad \tau \ge 2, \quad P_{+}(1) = P_{OFF}(1)$$
(2)

# **Ingredients II**

#### Imposed graph property distribution

- Rejection Sampling based on a Metropolis-Hastings algorithm
- ▶ new state  $G'_t = \{G_t + S_e(t) \text{ changed}\}$ , is accepted with probability  $P_{RS}(G_t, G'_t) = \min\left(1, \frac{F(x(G'_t))}{F(x(G_t))}\right)$
- F is the target PDF for the graph
- ► The total probability of transition of link *e* is then:  $P_{tr}(e, G_t) = P_{-/+}(\tau(e)) \cdot P_{RS}(G_t, G'_t).$

# **Ingredients III**

#### Imposed dynamics of triangles

- reproduce the correct dynamical transition process concerning triangles
- do not want to change the mean probabilities of transition
- The weighted probabilities are then:

$$egin{aligned} \mathcal{P}_{tr}(m{e},G_t) = \left\{ egin{aligned} \mathcal{P}_+( au(m{e}))rac{\mathcal{P}_{+/tri=}}{f_{+/tri=}} \ \mathcal{P}_+( au(m{e}))rac{\mathcal{P}_{+/tri+}}{f_{+/tri+}} \end{aligned} 
ight. \end{aligned}$$

for link creation without new triangle,

for link creation with a new triangle.

### Simulation results

#### Investigated models

- A: imposed empirical contact and inter-contact duration distribution only.
- B: imposed distributions of contact / inter-contact durations , and of number of connected components.
- C: distributions imposed contact / inter-contact durations and of number of connected vertices.



 $-- \text{ Imote / o Model } \mathcal{A} \, / * \, \text{Model } \mathcal{B} \, / + \, \text{Model } \mathcal{C}$ 



-- Imote / o Model  $\mathcal{A}$  / \* Model  $\mathcal{B}$  / + Model  $\mathcal{C}$ 

#### $\mathcal{A}$ : sole contact and inter-contact duration fails

- the number of connected vertices is strongly over-estimated
- the number of connected components is under-estimated



#### $\mathcal{A}, \mathcal{B} \text{ and } \mathcal{C} \text{ fail!}$

- The density of the connected components (the groups) is underestimated
- Links are spread uniformly in the graph



### Weighted models

- does not have an impact on the contact and inter-contact duration distributions
- the density of connected components is comparable to the experimental data



#### Density of frequent connected components

- (
   *τ* = 7 and 
   *σ* = 6
   )
- classical models fail to create dense frequent connected components
- the number of frequent connected subgraphs is larger in the simulated data than in the original

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#### contributions

- rigorous / coherent set of properties (basic / advanced)
- probability distribution of contacts and inter contacts is only one parameter
- global analyses to characterize the dynamics of the graph as a whole:
  - correlation between links
  - stability of the connected components
  - number of triangles
  - evolution of communities inside the interaction networks.
- simple / accurate models that generate random interaction graphs with satisfactory temporal properties.

### Conclusion

#### Futur / On going works

- Introduce non-stationarity (piecewise stationary model)
- Dynamic community computation
- Overlapping community detection
- Trajectories of individuals as a signature
- Large in situ test beds to be deployed...

### Some references

#### Dynamic networks

- Antoine Scherrer, Pierre Borgnat, Éric Fleury, Jean-Loup Guillaume and Céline Robardet, *Description and simulation of dynamic mobility networks*, in Computer Network 2008.
- Pierre Borgnat, Éric Fleury, Jean-Loup Guillaume, Céline Robardet and Antoine Scherrer, Analysis of Dynamic Sensor Networks: Power Law Then What?, in Comsware 2007.